Sentinel-1 System Capabilities and Applications





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Global Monitoring for Environment and Security (GMES)

- esa
- EU/ESA co-funded program aiming at providing operational GMES services based on Earth observation and in-situ data
- Provides relevant information to policy-makers, institutional EU + Member States authorities (Core service), and local/regional users (Downstream)
- Space Component developed & coordinated by ESA
 - ✓ Sentinels (1-5)
 - ✓ Contributing (national) Missions Data Access

In-situ component – coordinated by EEA

- ✓ Observations mostly within national responsibility, with coordination at European level
- $\checkmark\,$ Air, sea- and ground-based systems and instrumentations

Service component – coordinated by EC

✓ Mapping and forecasting services:

Land, Marine, Atmosphere, Emergency, Security and Climate Change











Sentinel-1 Mission Objectives and Requirements

- Provide routinely and systematically SAR data to GMES services and National services focussing on the following applications:
 - ✓ Monitoring of marine environment (e.g. oil spills, sea ice zones)
 - ✓ Surveillance of maritime transport zones (e.g. European and North Atlantic zones)
 - ✓ Land Monitoring (e.g. land cover, surface deformation risk)
 - ✓ Mapping in support of crisis situations (e.g. natural disasters and humanitarian aid)
 - ✓ Monitoring of Polar environment (e.g. ice shelves and glaciers)

















Sentinel–1 Mission Facts

- Constellation of two satellites (A & B units)
- C-Band Synthetic Aperture Radar Payload (at 5.405 GHz)
- 7 years design life time with consumables for 12 years
- Near-Polar sun-synchronous (dawn-dusk) orbit at 698 km
- 12 days repeat cycle (1 satellite), 6 days for the constellation
- Both S-1 satellites are in the same orbital plane (180 deg. phased in orbit)
- On-board data storage capacity (mass memory) of 1400 Gbit
- Two X-band RF channels for data downlink with 2 X 260 Mbps
- On-board data compression using Flexible Dynamic Block Adaptive Quantization (FDBAQ)
- Optical Communication Payload (OCP) for data transfer via laser link with the GEO European Data Relay Satellite (EDRS)
- Launch of Sentinel-1A scheduled for first Quarter of 2014 followed by Sentinel-1 B 18 months later









Sentinel–1 System Overview





Sentinel-1 SAR Imaging Modes

(1/2)



• Instrument provides 4 exclusive SAR modes with different resolution and coverage



- Polarisation schemes for IW, EW & SM:
 - ✓ single pol: HH or VV
 - ✓ dual pol: HH+HV or VV+VH
- Wave mode: HH or VV

SAR duty cycle per orbit:

- ✓ up to 25 min in any imaging mode
- ✓ up to 74 min in Wave mode

Main mode of operations: *IW*

satisfies most GMES user/service requirements (i.e. resolution, swath width, polarisation)

WV mode is continuously operated over open ocean

Sentinel-1 SAR Imaging Modes

(2/2)



Mode	Incidence Angle	Single Look Swath Width Resolution		Polarisation	Chirp bandwidth [MHz]	
Interferometric Wide Swath (IW 1-3)	30-42 deg.	Range 5 m Azimuth 20 m	250 km	HH+HV or VV+VH	56.50 - 42.80	
Wave mode WV1 WV2	23 deg. 36.5 deg.	Range 5 m Azimuth 5 m	20 x 20 km Vignettes at 100 km intervals	HH or VV	74.5 48.2	
Strip Map S1-S6	20-43 deg.	Range 5 m Azimuth 5 m	80 km	HH+HV or VV+VH	87.60 – 42.20	
Extra Wide Swath (EW 1-5)	20-44 deg.	Range 20 m Azimuth 40 m	400 km	HH+HV or VV+VH	22.20 – 10.40	
Image						
Radiometric Accuracy						
Noise Equivalent Sigm						
Point/Distributed Targe	Gmes					
Phase Error over 10 m	We care for a safer world					

Sentinel-1 Reference Scenario Coverage



Average Revisit Time S-1A Satellite



Average Revisit Time with S-1A + S-1B Satellites



	S-1A Satellite After 12 days				S-1A + S-1B Satellites After 6 days					
Complete global coverage										
	lce	MTZ	Europe	Canada	Rest of Land	Ice	MTZ	Europe	Canada	Rest of Land
Number of acquisitions (range from - to)	1-9	1-6	1-5	1-4	1-6	2-18	2-12	2-10	2-8	2-12
Average Revisit Time [day]	8,0	3,7	5,5	8,2	9,9	5,0	1,9	2,7	4,1	4,9



Sentinel-1 SAR TOPS Mode



TOPS (Terrain Observation with Progressive Scans in azimuth) for Sentinel-1 *Interferometric Wide Swath (IW)* and *Extended Wide Swath* (EW) modes

- ScanSAR-type beam steering in *elevation* to provide large swath width (IW: 250 and EW: 400km)
- Antenna beam is steered along *azimuth* from *aft* to the *fore* at a constant rate
 - ✓ All targets are observed by the entire azimuth antenna pattern *eliminating scalloping effect* in ScanSAR imagery
 - ✓ Constant SNR and azimuth ambiguities
 - ✓ Reduction of azimuth resolution (decrease in dwell time)
 - S-1 TOPS mode parameters: ±0.8° azimuth scanning at PRI rate with step size of 1.6 mdeg
- TOPS was first demonstrated by DLR with TerraSAR-X through ESA funded study





TSX-ScanSAR image



Sentinel-1 IW Mode Image Data Block





Sentinel-1 Orbital Tube and InSAR Baseline



- Satellite will be kept within an *Orbital Tube* around a Reference Mission Orbit (RMO)
- Orbital Tube radius (statistical) with 50m (rms)
- Orbit control is achieved by applying across-track dead-band control at the most Northern point and Ascending Note crossing





- Sentinel-1 A & B will fly in the same orbital plane with *180 deg.* phased in orbit
- 12-day repeat orbit cycle for each satellite
- Formation of SAR interferometry (InSAR) data pairs having time intervals of *6-days*



• S-1 TOPS InSAR study based on TerraSAR-X TOPS data, e.g. acquired over Atacama desert (Chile) having 11-day repeat pass interval



 Coherence loss in ScanSAR due to SNR degradation at burst edges (after azimuth pattern correction)

Image courtesy: P. Prats, DLR

- TOPS interferogram generation requires burst synchronization of repeat-pass datatakes
- TOPS burst duration for:
 - ✓ EW: 0.54 s (worst case)
 - ✓ IW : 0.82 s (worst case)
- S-1 requirement for Burst Synchronization: ≤ 5ms





Sentinel-1 TOPS InSAR Capabilities



- Antenna squint in Stripmap mode images induces linear phase ramps in the Impulse Response Function (IRF) ⇒ small co-registration error causes InSAR phase offset
- TOPS mode: Azimuth phase ramp (azimuth fringes) is introduced due to small co-registration errors along with Doppler centroid variations (5 kHz) due to azimuth scanning



Sentinel-1 Attitude Steering Modes



plane

Roll-steering mode

- Sensor altitude changes around the orbit
- Introduction of additional satellite *roll angle* depending on latitude to maintain a quasi "*constant*" *slant range*

 H_{max}

 θ_{ref}

Href

at Hmin = 697.6 km $\Rightarrow \theta_{\text{off-Nadir}} = 30.25^{\circ}$ at Hmax = 725.8 km $\Rightarrow \theta_{\text{off-Nadir}} = 28.65^{\circ}$

Advantages:

- Single PRF round orbit per swath or subswath (except for S5 (S5-N and S5-S)
- Fixed set of constant *Elevation antenna beam patterns*

Total zero-Doppler steering mode

- Yaw and pitch adjustments around the orbit to account for Earth rotation effect
- Provides Doppler centroid at about 0 Hz





Sentinel-1 Observation Strategy



SAR mode selection is based on optimum use of SAR duty cycle (25 min/orbit)

- ✓ satisfies most GMES user/service requirements (i.e. resolution, swath width, polarisation)
- $\checkmark\,$ increases revisit time and coverage
- $\checkmark\,$ enables build-up of long time series of data
- \checkmark high level of automation for mission planning
- $\checkmark\,$ pre-defined operations to the maximum extent possible
- minimize potential conflicts during operations, considering constraints (e.g. mode transition time, X-band switches)



- Over *land* and *maritime shipping routes*: *IW* is pre-defined mode
- Over Polar areas (i.e. sea ice): IW (or EW) is pre-defined mode
- Emergency observation requests may alter the pre-defined observation scenario: use of the SM mode
- Over open ocean: WV mode is continuously operated



Sentinel-1 Marine Applications: Oil Spill & Sea-Ice Monitoring







Sentinel-1 Mission Performance Analysis Example: Ship Detection





Sentinel-1 Data Access Timeliness



Data access to systematically generated products is provided according to the following timeliness:

- Standard timeliness: within 24h from sensing for all systematic products
- NRT timeliness:
 - < 3h from sensing (within 1h from downlink)</p>
 - In from sensing for data acquired in direct downlink



Sentinel-1 SAR Product Slicing



- Level-1 products are segmented in "slices" of defined length along track, optimised per mode and product type
- Level-1 slices cover a sub-set of the data take in along-track direction and the complete datatake area in the across-track direction
- Slices are in the nominal product type projection (slant-range for SLC, ground range for GRD)
- Slices are stand-alone products and can be handled separately in terms of archiving and dissemination
- Slices are seamlessly "concatenable" into a continuous product covering the complete datatake



Sentinel-1 In-Orbit Commissioning Phase Activities



Spacecraft and end-to-end SAR System performance verification and calibration

- Check-out of spacecraft and ground segment
- In-orbit verification of instrument performance and calibration:
 - ✓ Internal instrument calibration using network of calibration pulses to monitor drift in Tx & Rx signal paths, and the entire antenna system (T/R modules) using pulse coded techniques (PCC)
 - ✓ Antenna pointing calibration (< 0.01°)</p>
 - ✓ Antenna model verification (0.2 dB (3σ) for absolute 2-way gain)
 - ✓ Absolute radiometric calibration (< 1 dB (3σ))
 - ✓ Radiometric stability (<0.5 dB (3σ))
 - ✓ Geometric calibration (pixel localization: 2.5m (3σ))
 - ✓ Polarimetric calibration
 - ✓ Interferometric verification
- Level 0 and Level 1b SAR product verification (i.e. wrt SAR instrument performance) To be completed within 3 months (Challenge!)



Current timeline consists of data acquisitions over:

- Transponder sites (3) in NL
- Lake area in NL for NESZ measurement
- Rainforest for antenna model verification and radiometric calibration
- Long data takes (25 minutes) for all modes
- DLR test site for complementary calibration activities (Corner reflectors and transponders)
- InSAR verification sites (systematic generation repeat-pass interferograms (e.g. Lake Uyuni, Atacama desert, Death Valley)
- Measurement of InSAR phase stability (closed loop phase) over Corner Reflector site at DLR

Sentinel-1 Commissioning Phase Calibration Sites















ESA Member States have adopted a *FREE* and *OPEN* data policy

Anybody can access Sentinel data; no difference is made between public, commercial and scientific use → open access

Sentinel data will be made available to the users via a 'generic' online access mode

→ free of charge

Data Policy still needs approval by the European Commission

→ security restrictions might be implemented on data distribution





Conclusions



- Using the same SAR imaging mode (instrument settings, e.g. IW) facilitates the build-up of *data time series* for long-term continuity of observations with *equidistant* and *short time intervals (interferogram stacks)*
- TOPS burst synchronization to enable TOPS InSAR
- Sentinel-1 A & B will fly in the same orbital plane with 180 deg. phased in orbit, each with 12-day repeat orbit cycle
- Formation of InSAR data pairs having time intervals of 6-days
- Small orbital tube with radius of 50m (rms) provides small InSAR baselines

⇒ Coherent Change Detection Monitoring applications

Monitoring of geophysical phenomena related to surface displacements and/or changes in scattering properties having different time scales (mm/year – m/day)

 Collaboration with CSA's RADARSAT Constellation Mission (RCM) to facilitate *multi-satellite SAR monitoring* ⇒ requires harmonization of data acquisition strategies and interfaces















Backup Slides



Sentinel-1 Data Acquisition Scenario



- Systematic data acquisition in main high rate IW/EW modes of max 25 min per orbit will generate large data acquisition segments
- Leads to about 2.4 TB/per day of compressed raw data for Sentinel-1 A & B



Sentinel-1 Mission Objectives and Requirements

- Provide C-band SAR data continuity (at 5.405 GHz)
- Data quality similar or better than ERS/ENVISAT (e.g. equalized performance across the swath)
- Complete global coverage within a single repeat orbit cycle (175 orbits in 12 days) and systematic revisit (greatly improved as compared to ENVISAT)
- Capability for repeat-pass SAR interferometry (i.e.TOPS InSAR)
- Systematic data acquisition to enable build-up of long observation time series
- High system availability (i.e. SAR duty cycle)
- Conflict-free operations w.r.t. SAR mode selection for data acquisition (swath width and polarization)
- On-board data latency (i.e. downlink) requires:
 - max 200 min (2 orbits)
 - One orbit for support of near real time (3h) applications
 - Simultaneous SAR acquisition and data downlink for real time applications











